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Interested committees: B/2 B/11 CB/1 B/526

Title: pr EN ISO 22476-2 Geotechnical engineering - Field testing -

Part 2: Dynamic probing

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Introduction

This draft standard is based on European discussions in which the UK took an active part. Your comments on this draft are welcome and will assist in the preparation of the consequent British Standard. If no comments are received to the contrary, then the UK will approve this draft and implement it as a British Standard. Comment is particularly welcome on national, legislative or similar deviations that may be necessary.

Even if this draft standard is not approved by the UK, if it receives the necessary support in Europe, the UK will be obliged to publish the official English Language text unchanged as a British Standard and to withdraw any conflicting standard.

UK Vote

Please indicate whether you consider the UK should submit a negative (with reasons) or positive vote on this draft.

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Document

National Committee	Clause/ subclause	Paragraph/ Figure/ Table	Type of comment (General/ technical/editorial)	COMMENTS	Proposed change	OBSERVATIONS OF THE SECRETARIAT
	3.1	1st definition	Editorial	Definition is ambiguous and needs clarifying.	Amend to read ' so that the mains connector to which no connection'	
	6.4		Technical	The use of the UV photometer as an alternative cannot be supported as serious problems have been encountered in its use in the UK.	Delete reference to UV photometer.	

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EUROPEAN STANDARD NORME EUROPÉENNE EUROPÄISCHE NORM

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English version

Geotechnical investigation and testing - Field testing - Part 2: Dynamic probing (ISO/DIS 22476-2:2002)

Reconnaissance et essai géotechnique - Essais en place -Partie 2: Essai de pénétration dynamique (ISO/DIS 22476:2002) Geotechnische Erkundung und Untersuchung -Felduntersuchungen - Teil 2: Rammsondierungen (ISO/DIS 22476-2:2002)

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If this draft becomes a European Standard, CEN members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this European Standard the status of a national standard without any alteration.

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Foreword

This document (prEN ISO 22476-2) has been prepared by Technical Committee CEN/TC 341, "Geotechnical investigation and testing", the secretariat of which is held by DIN, in collaboration with Technical Committee ISO/TC 182 "Geotechnics".

This document is currently submitted to the parallel Enquiry.

Annexes A and B are normative; annexes C, D and E are informative.

EN ISO 22476 Geotechnical engineering - Field testing has the following parts:

- Part 1: Cone and piezocone penetration tests
- Part 2: Dynamic probing
- Part 3: Standard penetration test
- Part 4: Borehole expansion tests

1 Scope

This European standard specifies requirements for indirect investigations of soil by Dynamic Probing within the scope of the geotechnical investigations according to ENV 1997.

This European standard covers the determination of the resistance of soils and soft rocks in situ to the dynamic penetration of a cone. A hammer of a given mass and given falling height is used to drive the cone. The penetration resistance is defined as the number of blows required to drive the penetrometer over a defined distance. A continuous record is provided with respect to depth but no samples are recovered.

Four procedures are included, covering a wide range of specific work per blow:

- Dynamic probing light (DPL): test representing the lower end of the mass range of dynamic equipment;
- Dynamic probing medium (DPM): test representing the medium mass range of dynamic equipment;
- Dynamic probing heavy (DPH): test representing the medium to very heavy mass range of dynamic equipment;
- Dynamic probing super heavy (DPSH): test representing the upper end of the mass range of dynamic equipment.

The test results of this European standard are specially suited for the qualitative determination of a soil profile together with direct explorations (e.g. drilling and sampling according to EN ISO 22475) or as a relative comparison of other in situ tests. They may also be used for the determination of the strength and deformation properties of soils, generally of the cohesionless type but also possibly in fine-grained soils, through appropriate correlations. The results can also be used to determine the depth to very dense ground layers indicating the length of end bearing piles, and to detect very loose, voided, backfilled or infilled ground.

2 Normative references

This European Standard incorporates by dated or undated reference, provisions from other publications. These normative references are cited at the appropriate places in the text and the publications are listed hereafter. For dated references, subsequent amendments to or revisions of any of these publications apply to this European Standard only when incorporated in it by amendment or revision. For undated references the latest edition of the publication referred to applies.

EN 1997-1, Eurocode 7: Geotechnical design — Part 1: General Rules.

EN 1997-3, Eurocode 7: Geotechnical design — Part 3: Design assisted by field testing.

EN 10204, Metallic products - Types of inspection documents.

EN ISO 22475, Geotechnical engineering – Drilling and sampling methods and groundwater measurements.

EN ISO 22476-3, Geotechnical engineering – Field tests – Part 3: Standard Penetration Test.

3 Terms and definitions

For the purpose of this European standard the following terms and definitions apply:

3.1

dynamic penetrometer

cone and drive rods

3.2

dynamic probing equipment

penetrometer and all equipment necessary to drive the penetrometer

3.3

anvil or drive head

that portion of the drive-weight assembly that the hammer strikes and through which the hammer energy passes into the drive rods

3.4

cone

pointed probe of standard dimensions used to measure the resistance to penetration (see Figure 1)

3.5

drive rods

rods that connect the drive-weight assembly to the cone

3.6

drive-weight assembly

a device consisting of the hammer, hammer fall guide, the anvil and the drop system

3.7

actual energy

EM

energy delivered by the drive-weight assembly into the drive rod immediately below the anvil, as measured.

3.8

theoretical energy

ET

energy as calculated for the drive weight assembly,

 $ET = m {\cdot} g {\cdot} h$

- *m* is the mass of the hammer
- *g* is the acceleration due to gravity
- *h* is the falling height of the hammer

3.9

energy ratio

 E_r

ratio of the actual energy EM and the theoretical energy ET of the hammer expressed in percentage.

3.10

hammer

that portion of the drive-weight assembly which is successively lifted and dropped to provide the energy that accomplishes the penetration of the cone

3.11

N-values

number of blows required to drive the penetrometer over a defined distance, expressed in centimetres by the corresponding sub-index (N_{10L} , N_{10M} , N_{10H} , N_{20SA} , N_{20SB})

4 Equipment

4.1 Cone

The cone of steel shall have an apex angle of 90° and an upper cylindrical extension mantle and transition to the extension rods as shown in Figure 1 and with the dimensions and tolerances given in Table 1. The cone may be sacrificial (lost) or retained (fixed) for recovery.



- 1 extension rod
- 2 injection opening (optional)
- 3 point mounting
- 4 cone tip
- 5 cone
- 6 mantle

Figure 1 – Alternative forms of cones for dynamic probing (for L, D and d_r see Table 1)

4.2 Drive rods

The rod material shall be of a high-strength steel with the appropriate characteristics for the work to be performed without excessive deformations and wear. The rods shall be flush jointed, shall be straight and may have spanner flats. The maximum axial deviation for any one rod shall not exceed 1 mm in 1000, i.e. 1 mm in 1 m. Dimensions and masses of the drive rods are given in Table 1.

Hollow rods should be used; solid rods may be used.

4.3 Anvil

The anvil shall be made of high strength steel. A damper or cushion may be fitted between the hammer and anvil.

4.4 Torque measuring wrench

The torque necessary to turn the driving rods is measured by means of a torque wrench. The apparatus shall be able to measure a torque of at least 200 Nm and be graduated to read at least all 5 Nm.

A sensor for recording the torque may be used.

The driving rods can include a spanner flat to fix the torque wrench.

4.5 Optional equipment

4.5.1 Blow counter

A device to count the number of blows of the hammer by measuring mechanical or electric impulses can be placed on the system.

4.5.2 Penetration length measuring device

The penetration length is measured either by counting on a scale on the rods or by recording sensors. In this latter case, resolution shall be better than 1/100 of the measure length.

4.5.3 Injection system

The injection system includes:

- hollow rods;
- a pump with mud connected to a device fixed under the anvil and intended to ensure the filling, of the annular space between the ground and the drive rods created by the enlarged cone.

The flow of the pump is such that it will always ensure that the annular space between the ground and the drive rods is filled.

NOTE 1 Mud, for example, can be a mixture of bentonite and water with a mass relationship between the dry particles and water is 5 % to 10 %.

NOTE 2 The mud circulation towards the surface is not obligatory. The pressure of injection is that corresponding, after deduction of the head losses, to the hydrostatic pressure due to mud on the level of the cone.

A manual pump may be used.

4.5.4 Apparatus for measuring the dimensions of the cone

The measurement of the diameter and length of the cone is made by means of a slide caliper to the 1/10 of mm or by an equivalent system.

Dynamic Probing Apparatus	Sym bol	Unit	DPL (light)	DPM (medium)	DPH (heavy)	DP (super	PSH r heavy)	
						DPSH-A	DPSH-B	
Driving device								
hammer mass, new	т	kg	$10 \pm 0,1$	$30\pm0,3$	$50\pm0,5$	$63,5\pm0,5$	$63,5\pm0,5$	
height of fall	h	mm	500 ± 10	500 ± 10	500 ± 10	500 ± 10	750 ± 20	
Anvil								
diameter	d	mm	$50 < d < D_{\rm h}^{\rm a}$	50< <i>d</i> < <i>D</i> _h ^a	50 <d<0,5 d<sub="">h^a</d<0,5>	50 <d<0,5 d<sub="">h</d<0,5>	50 <d<0,5 d<sub="">h^a</d<0,5>	
mass (max.)	т	kg	6	18	18	18	30	
(guide rod included)								
90° Cone								
nominal base area	Α	cm ²	10	15	15	16	20	
base diameter, new	D	mm	$35,7\pm0,3$	$43,7\pm0,3$	$43,7\pm0,3$	45,0± 0,3	51 ± 0,5	
base diameter, worn (min.)		mm	34	42	42	42	49	
mantle length (mm)	L	mm	35,7 ± 1	43,7 ± 1	43,7 ± 1	$90,0\pm2^{b}$	51 ± 2	
tapper angle upper		o	11	11	11	0	11	
length of cone tip		mm	$17,9\pm0,1$	$21,9\pm0,1$	$21,9\pm0,1$	$22,5\pm0,1$	$25{,}3\pm0{,}4$	
tip max. permissible wear		mm	3	4	4	5	5	
Drive rods ^c								
mass (max)	т	kg/m	3	6	6	6	6	
diameter OD (max)	d _a	mm	22	32	32	32	32	
rod deviation:								
lowermost 5 m		%	0,1	0,1	0,1	0,1	0,1	
remainder		%	0,2	0,2	0,2	0,2	0,2	
Specific work per blow	mgh/A	kJ/m ²	50	100	167	194	238	
^a D. diamater of the hammer, in case of rectangular shape, the smaller dimension is assumed to be equivalent to the diamater								

Table 1 — Dimensions and masses for the four types of dynamic probing apparatus

nmer, in case of rectangular shape, the smaller dimension is assumed to be equivalent to the diam

^b sacrificial cone only

° maximum rod length shall not exceed 2 m

NOTE Tolerances given are manufacturing tolerances

4.6 Equipment checks and calibrations

Prior to each test, a check of dimensions shall be made to ensure that they are within the values given in Table 1. The straightness of the rods shall be checked once on each new site and at least every 20 penetration tests at that site.

At the test site, the rate of blows, the height of fall, the friction free fall of the hammer, the proper condition of the anvil and the mechanical release devices shall be checked for satisfactory operation which is to be ensured for the whole test series. In addition, the proper functioning of the recording device has to be checked in case automatic recording equipment is used.

The precision of the measuring instruments – if applicable - shall be checked after any damage, overloading or repair but at least once every six months, unless the manufactures specify shorter inspection intervals. Faulty parts shall be replaced. Calibration records shall be kept together with the equipment.

To check pneumatic dynamic penetrometers, the driving energy per impact referred to the cone area shall be measured directly. This shall not deviate from the theoretical value as specified in Table 1 by more than 3 %. Manufacturers of pneumatic dynamic probing equipment shall provide factory certifications as stipulated by EN 10204 together with each unit they supply. The user shall have such penetrometers checked every six months.

Energy losses occur e.g. due to friction at the hammer (velocity loss compared to the free fall) or due to energy losses during the hammer impact on the anvil. Therefore also for the free-fall equipment, it is generally recommended to know by calibration the actual energy transmitted to the drive rods. An example for the method to determine the actual energy is given in Annex D.

4.7 Driving device

Dimensions and masses of the components of the driving device are given in Table 1. The following requirements shall be fulfilled:

- a) the steel hammer shall be conveniently guided to ensure minimal resistance during the drop;
- b) the automatic release mechanism shall ensure a constant free fall, with a negligible speed of the hammer when released and no induced parasitic movements in the drive rods;
- c) the steel drive head or anvil should be rigidly connected to the top of the drive rods. A loose connection can be chosen.

5 Test procedure

5.1 Test preparation

In general, dynamic probing is performed from the ground surface; the number of blows N_{10} or N_{20} is recorded continuously.

Dynamic probing test equipment shall be set up with the penetrometer vertical, and in such a way that there will be no displacement during testing. The inclination of the driving mechanism and the driving rod projecting from the ground shall not deviate by more than 2 % from the vertical; in difficult ground conditions deviations up to 5 % may be allows provided that they are reported. If this is not the case, the dynamic probing test shall be started anew.

Trailer-mounted dynamic probing test equipment shall be supported in such a way that the suspension travel of the support trailer cannot influence the test. The equipment shall be set up with appropriate clearance from structures, piles, boreholes etc., in order to be certain that they will not influence the result of the dynamic probing test.

When carrying out dynamic probing in situations where the rods are free to move laterally, for instance in surface waters and boreholes, the rods shall be restrained by low-friction supports in order to prevent bowing during driving or when the penetration force is applied.

5.2 Test execution

The drive rods and the cone shall be driven vertically and without undue bending of the protruding part of the extension rods above the ground.

No load shall be applied to anvil and rods during lifting of the hammer.

The penetrometer shall be continuously driven into the ground. The driving rate shall be kept between 15 and 30 blows per minute, except when known to be penetrating sand and gravel, where the driving rate may be increased up to 60 blows per minute. All interruptions longer than 5 minutes shall be recorded.

The rods shall be rotated 1½ turns at least every 1,0 m and the maximum torque required to turn the rods shall be recorded.

For rotating the rods, a torque measuring wrench or an equivalent torque measuring device shall be used.

To decrease skin friction, drilling mud or water may be injected through horizontal or upwards holes in the hollow rods near the cone. A casing is sometimes used with the same purpose.

The number of blows shall be recorded every 10 cm for the DPL, DPM and DPH and every 20 cm for the DPSH-A and DPSH-B.

The normal range of blows, especially in view of any quantitative interpretation of the test results according to ENV 1997-3, is between $N_{10} = 3$ and 50 for DPL, DPM and DPH and between $N_{20} = 5$ and 100 for DPSH-A and DPSH-B. For specific purposes, these ranges may be exceeded. In cases beyond these ranges, when the penetration resistance is low, e.g. in soft clays, the penetration depth per blow may be recorded. In hard soils or soft rocks, where the penetration resistance is very high, the penetration for a certain number of blows may be recorded.

5.3 Safety requirements

National safety regulations shall be followed; e. g. regulations for:

- personal health- and safety equipment;
- ear protectors;
- clean air, if working inside;
- ensuring the safety of the equipment.

6 Interpretation of tests

The tests shall be interpreted based on values of N_{10} for DPL, DPM, DPH and N_{20} for DPSH-A and DPSH-B.

Another possibility for the interpretation of test results is the use of the dynamic point resistance (see Annex E).

Consideration shall be given to the fact that the rod friction will influence *N*-values recorded (see e.g. Annex C).

Due to energy losses, when this test is used for quantitative evaluation purposes, it is recommended to know by calibration the actual energy *EM* transmitted to the drive rods.

7 Reporting of results

7.1 Field report

At the project site, a summary log according to Annex A shall be completed. Test records according to Annex B are to be used to record the data of each test. The number of blows N_{10} or N_{20} , as applicable as well as the measured torque are to be recorded as a function of depth.

The following additional information shall be documented:

- weather condition;
- interruption of the probing operations with time duration, and change of rods;
- each unusual event or observation during the operation (e.g. low blow count, rebound > 50 %, penetration without blows, temporary obstructions, artesian conditions, reasons for early end of probing);
- use of any separate precautions against rod friction, e.g. casings or fluids;
- observations on the recovered cone.

7.2 Test report

In the test report, the results of the test shall be presented to scale as step diagram with results of the dynamic probing on the horizontal axis and the depth on the vertical axis.

All field investigations are to be reported about in such a fashion that third persons are able to check and understand the results.

For the purpose of identification and quality assurance, the test report shall include the following information:

- a) Name of company executing the test;
- b) identification of the actual site or area;
- c) date of test;
- d) location and elevation of each test;
- e) the type of dynamic probing: DPL, DPM, DPH, DPSH-A or DPSH-B; all divergences from these test procedures shall be described in detail;
- f) manufacturer of equipment, lost or fixed cone and fixed or loose anvil, use of dampers;
- g) a graphical representation with respect to depth of the following data:
 - the recorded number of blows to drive the cone 10 cm for the DPL, DPM and DPH or 20 cm for the DPSH-A and DPSH-B;
 - the maximum torque required to rotate the penetrometer at each test level (in Nm),
 - all interruptions during the work, longer than 5 minutes;
- h) the use of any separate precaution against friction such as casing, drilling mud or water;
- i) any corrections in the presented data;
- j) blow count frequency when operating the equipment;
- k) details of any unusual event during driving, e.g. penetration without blows, temporary obstructions, artesian conditions.
- I) reasons for the end of the test;
- m) the signature of the operator in charge, or the field manager.

8 Additional factors influencing the results of dynamic probing

8.1 General

The following factors can effect the results:

- geotechnical influences and
- equipment influences.

In order to avoid misinterpretation of the dynamic probing results, these factors should be considered; also findings from direct soil explorations (e.g. drilling and sampling methods according EN ISO 22475) have to be available.

8.2 Geotechnical influences

8.2.1 Influence of soil type, soil group and soil characteristics

For coarse-grained soils for example, apart from density, the grain structure, the grain size distribution, the grain shape and grain roughness, the mineral type, the degree of cementation and the strain condition in the soil can effect the results.

Examples for influences of soil type, soil group and soil characteristics are given in Annex C.1 to C.3.

An example for the influence of the boundary depth is given in Annex C.4.

For fine grained soils, rod friction can have a significant influence on the recorded blow count. The use of drilling mud and water can reduce this effect (Annex C.2).

8.2.2 Influence of the groundwater

Under otherwise equal soil conditions, the number of blows in coarse-grained soils is lower below the groundwater level; this is particularly marked for low penetration resistances. Examples of the influence of the ground water are given in Annex C.5.

Under otherwise equal soil conditions, the number of blows in silty soils is higher below the ground water level.

8.3 Equipment influences

To be considered as equipment influences on the penetration resistance are:

- cone diameter;
- rod length and deviation;
- energy losses within the drive systems.

Examples for some of the equipment influences are given in Annex C.6.

Annex A

(normative)

Summary log for dynamic probing

Only the content of the summary log is normative. The user is free to create a different format.

Place within which or which is nearest to*) location of penetration test:

X,Y,Z coordinates:	
Client/job number:	
Name and location of project:	
Contractor:	Equipment operator:
Date of test:	

Type of dynamic probing *): DPL, DPM, DPH, DPSH-A, DPSH-B:

Equipment checked and in accordance with EN ISO 22476-2, 4.4; Yes/No*) on: _____

Signature:_____

Name of the operator in charge or field manager: ___

Annex B

(normative)

Test record for dynamic probing

Only the content of the test record is normative. The user is free to create a different format.

Contrac	Contractor: Job number: Enclosure:								
Name of	Name of project:								
Dynam	Dynamic probing test No: Date:								
Type of dynamic probing test*): DPL, DPM, DPH, DPSH-A, DPSH-B or:									
Lost/fixed cone *) Fixed/loose anvil *)									
X, Y, Z	X, Y, Z coordinates								
Depth;	add 10, 20 o	<u>r 30 m (a</u>	is depth $> 10 \text{ m}$	<u>1): +</u>	m				
Depth	N ₁₀ /N ₂₀ *)	Depth	N ₁₀ /N ₂₀ *)	Depth	N ₁₀ /N ₂₀ *)	Depth	N ₁₀ /N ₂₀ *)	Depth	N ₁₀ /N ₂₀ *)
0,10		2,10		4,10		6,10		8,10	
0,20		2,20		4,20		6,20		8,20	
0,30		2,30		4,30		6,30		8,30	
0,40		2,40		4,40		6,40		8,40	
0,50		2,50		4,50		6,50		8,50	
0,60		2,60		4,60		6,60		8,60	
0,70		2,70		4,70		6,70		8,70	
0,80		2,80		4,80		6,80		8,80	
0,90		2,90		4,90		0,90		8,90	
1,00	Nim	3,00	Nim	5,00	Nime	7,00	Nizz	9,00	Nim
1.10	INITI	2.10	INIII	E 10	INITI	7 10		0.10	INITI
1,10		3,10		5,10		7,10		9,10	
1,20		3,20		5,20		7,20		9,20	
1,30		3,30		5,30		7,30		9,30	
1,40		3,40		5,40		7,40		9,40	
1,50		3,50		5,50		7,50		9,50	
1,00		3,00		5,00		7,00		9,00	
1,70		3.80		5.80		7,70		9.80	
1,00		3.90		5 90		7,00		9.90	
2 00		4 00		6.00		8 00		10.00	
**)		**)		**)		**)		**)	
*) De	elete as appli	cable.		/		/		/	
**) me	easured toral	le							
,									
-									
Other d	lata								
Ground	lwater:	m below	starting point						
	and also de	- 6 41							
Name and signature of the operator in charge or field manger:									

Annex C

(informative)

Examples for geotechnical and equipment influences on the dynamic probing results

C.1 Examples for results of dynamic probing in coarse-grained soils

Other conditions remaining the same, the following applies:

- a) The penetration resistance increases more than linearly with increasing relative density of the soil; thus a change in relative density, for example as a result of deep compaction, can be detected by dynamic probing;
- b) soils with sharp-edged or rough particles possess a higher penetration resistance than soils with round and smooth particles;
- c) cobbles and boulders can significantly increase the penetration resistance;
- d) particle size distribution (uniformity coefficient and grading curve) influence the penetration resistance;
- e) penetration resistance is considerably increased by cementation.

Figure C.1 shows the results of a light dynamic probing test (DPL) in backfilled soil.



Key

- 1 Medium and coarse sand
- ID Relative density
- d Depth

Figure C.1 — Change in penetration resistance with relative density in a homogeneous backfilled soil

The test were made in a test pit in which medium and coarse sand had been placed in layers of different relative densities. The penetration resistance increases sharply with increasing relative density of the soil; the indication thus becomes more sensitive.

Figure C.2 shows the increase in penetration resistance when there are thin layers with embedded cobbles. Locally occurring peaks of penetration resistance do not represent a measure of the bearing capacity of the whole layer.



- 1 Medium silt, fine-sandy with layers of stones
- d Depth

Figure C.2 — Increase in penetration resistance due to embedded cobbles

Figure C.3 shows that penetration resistance fluctuates more sharply in coarse-grained soils than in fine grained soils. The range of variation is more pronounced in gravels than in sands.

The absolute variations in penetration resistance obtained with a light dynamic penetrometer (DPL) do not result only from differing relative densities but also from the larger penetration resistance due to displacing or breaking up of embedded larger particles.



Key

- 1 Silt, sandy
- 2 Silt
- 3 Gravel
- d Depth

Figure C.3 — Variations in penetration resistance in fine-grained and coarse-grained soils

Figure C.4 shows the effect of cementing of the particles of a sand layer on the penetration resistance to a light dynamic penetrometer (DPL). This type of cementing may remain undetected with borings. The cementing was observed in trial pits.



- 1 Loam
- 2 Clay
- 3 Medium sand, cemented
- 4 Medium sand
- d depth

Figure C.4 — Increase in penetration resistance in a cemented medium sand

C.2 Examples for results from dynamic probing in fine-grained soils

In soft soil types the skin friction along the rod has considerable influence on the penetration resistance. This may mean, for example, that cavities in the subsoil are not recognised as such.

Figure C.5 shows that the Standard Penetration Test (SPT), unlike the result produced by the heavy dynamic penetrometer (DPH), shows virtually the same penetration resistances in clay because here the skin friction along the rod has been eliminated by performing the SPT in a borehole.



Key

- 1 Fill earth
- 2 Silt, sandy, gravely
- 3 Gravel, sandy
- 4 Clay
- d depth

Figure C.5 — Increase in penetration resistance as a result of skin friction along the rod using a heavy dynamic penetrometer (DPH) compared with the Standard Penetration Test (SPT)

Figure C.6 shows DPM profiles driven with and without the aid of drilling mud. The drilling mud reduces the friction on the drive rods allowing penetration to greater depth. This data has not been corrected for friction using the torque measurements.



Figure C.6 — Reduction of skin friction due to drilling mud

Figure C.7 shows the DPM data from Figure C.6 corrected using the torque readings to correct for the effect of friction on the rods. The correction reduces the N_{10M} values at the deeper depths and presents a reproducible depth profile both with and without the drilling mud.





Figure C.8 shows the result of a dynamic probing using the light dynamic penetrometer (DPL) in relation to structural changes in a soil in:

- a) natural silt and
- b) filled, only slightly compacted silt.



- 1 Medium silt, weak, clayey (loess loam)
- d depth
- a) natural silt
- b) filled, only slightly compacted silt.

Figure C.8 — Penetration resistance in natural silt and in filled, only slightly compacted silt

Figure C.9 shows that a decomposed peat has a very low penetration resistance.



Key

- 1 Silty clay
- 2 Peat decomposed
- 3 Clay, sandy, very silty
- d depth

Figure C.9 — Dynamic probing in decomposed peat

Figure C.10 shows that a fibrous, barely decomposed peat shows high levels of penetration resistance, including skin friction. Similiar effects can be observed in highly organic clays and silts.



- 1 Gravel and sand
- 2 Peat, fibrous
- 3 Fine sand and silt, slightly clayey
- d depth

Figure C.10 — Dynamic probing in fibrous, barely decomposed peat

C.3 Example for results of dynamic probing in mixed-grained soils

Since these influences overlap, the possibility of an incorrect interpretation is relatively great.

Figure C.11 shows the fluctuations in penetration resistance using a medium dynamic penetrometer (DPM) in various types of soil. The fluctuations are greater in soils with mixed grain sizes (e.g. silty coarse sand) owing to the higher proportion of coarse grains, than in fine-grained soils with organic admixtures (e.g. lake marl).



- 1 Fill
- 2 Clayey sand, gravel, silty
- 3 Peat
- 4 Lake marl with remnants of plants
- 5 Clayey lake marl
- 6 silty coarse sand, fine-sand
- d depth

Figure C.11 — Variations in penetration resistance in various soils

C.4 Example for penetration resistance results in shallow depths

In coarse-grained soils, the boundary or critical depth (1 to 2 m below the ground surface) increases with relative density and cone diameter. In addition, the penetration resistance increases sharply until the boundary depth is reached. Below the boundary depth, the penetration resistance remains nearly constant under otherwise equal conditions.

The overburden of the layer investigated (e.g. by back-fill) or any additional loading of the subsoil (e.g. foundation loads) may increase the penetration resistance.

Figure C.12 shows two results of dynamic probing with a light dynamic penetrometer in a test pit in which a coarse sandy medium sand of the same density throughout the depth has been laid. The test carried out from the surface of the back-fill showed initially an increase in penetration resistance with depth and then a virtually constant value. After removing a 1,30 m thick layer, a second test was carried out. This showed, starting from the new surface, initially a lower penetration resistance in the zones near the surface compared with the first test, but after a sharp increase in penetration resistance it gave the same values at greater depths as the first test, i. e. from the surface of the back-fill.



- a) Test from the surface of the back-fill
- b) Test from the bottom of the pit
- 1 Surface of back-fill
- 2 Bottom of pit
- 3 Coarse medium sand, dense
- d depth

Figure C.12 — Low penetration resistance in the zone near the surface of a dense medium sand

C.5 Example for the influence of groundwater

In coarse-grained soils, other conditions being the same, the penetration resistance in groundwater is lower than above the groundwater.

In fine-grained soils, owing to the capillary effect, the groundwater has little influence on penetration resistance. The penetration test results may be influenced by porewater pressures and groundwater flow.

The results shown in Figure C.13 show the influence of groundwater in coarse-grained soils. Where there is groundwater, lower penetration resistances are measures even if the relative density is the same.



Key

- a) No groundwater
- b) Groundwater at 0,2 m below the surface of the terrain
- 1 Fine and medium sand
- d depth

Figure C.13 — Change in the penetration resistance of a fine and medium sand as a result of groundwater

The following is an example of quantifying the influence of groundwater on dynamic probing test results in cohesionless soils. Comparative tests were conducted with DPL and DPH in a poorly graded sand (SP) and with DPH in a well graded sand-gravel mixture (GW) under controlled conditions above and below groundwater level. Figure C.14 shows the corresponding relations of number of blows N_{10L} and N_{10H} above to number of blows N_{10L} and N_{10H} below groundwater. The relations have the general form $N_{10} = a_1 N_{10} + a_2$; they are of deterministic nature and conservative estimates.



Soil classification	Uniformity coefficient	Coefficients			
		DPL		DPH	
	$U_{\rm c} = d_{60}/d_{10}$	<i>a</i> ₁	<i>a</i> ₂	<i>a</i> ₁	<i>a</i> ₂
SP	≤ 3	2,0	2,0	1,3	2,0
GW	≥ 6	-	-	1,2	4,5

- 1 Number of blows N'10L and N'10H below groundwater
- 2 Number of blows *N*_{10L} and *N*_{10H} above groundwater

SP poorly graded sand

GW well graded sand-gravel mixture

Figure C.14 — Examples of the influence of ground water on dynamic probing results

C.6 Examples for equipment influences

In dynamic probing, penetration resistance increases with increasing cross-section of the penetrometer cone. Penetration resistance is influenced to an extent that depends on how the ratio of cone diameter to rod diameter affects skin friction along the rod. This influence also depends on the type of soil, the sequence of layers and the depth of penetration.

In fine-grained soils, when the ratio of cone cross-section to rod diameter is small the skin friction along the rod can increase rapidly.

Figure C.15 shows that in layers near the surface the penetration resistance is generally greater with a larger penetrometer cone diameter than with the smaller cone diameter at constant rod diameter. In deeper layers, the change in penetration resistance depends on the type and condition of the soil. Thus with dynamic probing in silt layers, the penetration resistance of a smaller cone diameter is greater compared with a larger cone diameter due to skin friction.

With the smaller cone diameter, the skin friction along the rod has a very substantial effect because the cone is only slightly wider than the rod.

With dynamic probing, other conditions remaining the same, a larger number of blows is necessary as the length of the rod increases, because the efficiency decreases.



Key

- a) larger cone diameter
- b) smaller cone diameter
- 1 Gravel, sandy
- 2 Silt, sandy, slightly clayey (stiff)
- 3 Silt, clayey (soft)
- d depth

Figure C.15 — Influence of the cross section of the cone on the results of dynamic probing

Figure C.16 shows N_{10} data from four different configurations of dynamic probing equipment. The sensitivity of the lighter weight configurations show greater variations within each soil layer and the heavier configurations give N_{10} values close to or lower than the recommended minimum acceptable value. Drilling mud was used to reduce the friction on the drive rods for all but the DPSH probing significantly reducing penetration depth.



- I crust
- II weathered till
- III unweathered till
- IV silty sand
- d depth



Annex D

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Example of a method to measure the actual energy

D.1 Principle

The measurement of the energy transmitted to the drive rods can be made by means of an instrumented section of rod positioned at a distance greater than 10 times the rod diameter below the point of hammer impact on the anvil.



Key

- Anvil
 Part of instrumented rod
- 3 Drive Rod
- 4 Strain gauge (measuring transducer)
- 5 Accelerometer
- 6 Ground
- F Force
- d_a diameter of the rod

Figure D.1 — Instrumented rod (example)

D.2 Equipment

The measuring device consists of a removable instrumented rod fixed between the anvil and the head of rods. It includes :

- a system for measurement of vertical acceleration having a linear response up to 5000 g;
- a system for measurement giving the axial deformation induced in the rod;
- an apparatus, with a resolution better than 1.10⁻⁵s, for viewing, recording and pre-treatment of the signals;
- data processing system (data logger and computer).

When strain gauges are used for the measurement of the axial deformation, they should be uniformly distributed around the instrumented rod, preferable in two orthogonal pairs.

D.3 Measurements

At each impact, check the correct operation of the measuring equipment and the sensors by displaying the results of measurements

It should be verified that the signals from the accelerometers and of the gauges are null before and after the impact

For the measurement of the acceleration and deformation, the precision should be better than 2 % of the measured value.

D.4 Calculation

D.4.1 The force *F* transmitted to the rods is calculated as follow:

$$F(t) = A_a \cdot E_a \cdot \varepsilon_m(t) \tag{D.1}$$

where

 $\varepsilon_{\rm m}(t)$ is the measured deformations of the instrumented rod at time t

*A*_a is the cross-sectional area of the instrumented rod

 $E_{\rm a}$ is the Young's modulus of the instrumented rod.

D.4.2 The particle velocity v(t) of the measurement section is calculated by integration of the acceleration a(t) with time *t*.

D.4.3 The basic equation for the energy *E* which passes into the drive rods is:

$$E(t') = \int_{0}^{t} F(t)V(t)dt$$
 (D.2)

where

E(t') is the driving energy which passes into the drive rod up to time t' after the impact.

Various methods for developing the above equation and additional information can be found in the bibliography.

C.4.4 The SPT hammer energy to take into account is the mean value obtained from at least five measures :

$$EM = \frac{1}{n} \sum_{1}^{n} E \tag{D.3}$$

D.4.5 The hammer energy ratio which characterises each dynamic penetrometer is given by :

$$E_r = \frac{EM}{ET} \le 1 \tag{D.4}$$

where ET = mgh

h is the falling height of the hammer

- *m* is the mass of the hammer
- g is the acceleration due to gravity



Figure D.2 — Example of a hammer energy measurement report

Annex E (informative)

Interpretation of test results by using the dynamic point resistance

The results from dynamic probing are usually presented as blows per 10 cm penetration (N_{10}) against depth as a straight field record and should be within the standard range of values (typically 3 to 50). The N_{10} values can be interpreted to give the unit point resistance r_d and the dynamic point resistance q_d . The value of r_d is an assessment of the driving work done in penetrating the ground. Further calculation, to produce q_d , modifies the r_d value to take account of the inertia of the driving rods and hammer after impact with the anvil. The calculation of r_d includes the different hammer weights, the height of fall and the different cone sizes. The different sizes and number of extension rods are included in the calculation of q_d , and so this should allow comparison of different equipment configurations.

Typically the equations used are:

$$r_{\rm d} = \frac{ET}{Ae} \tag{E.1}$$

or

$$r_{\rm d} = \frac{EM}{Ae} \tag{E.2}$$

and

$$q_{\rm d} = \left(\frac{m}{m+m'}\right) r_{\rm d} \tag{E.3}$$

where

 $r_{\rm d}$ and $q_{\rm d}$ are resistance values in Pa

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m	is the	mass	ortine	nammer	ш	ĸy

- g is the acceleration due to gravity in m/s².
- *h* is the height of fall of the hammer in m
- *A* is the area at the base of the cone in m²
- *e* is the average penetration in m per blow $(0, 1/N_{10}$ from DPL, DPM, DPM, and DPH, and $0, 2/N_{20}$ from DPSH)
- N₁₀ is the number of blows per 100 mm
- N₂₀ is the number of blows per 200 mm

m' is the total mass of the extension rods, the anvil and the guiding rods at the length under consideration, in kg

The Figure E.1 gives data from DPL, DPM ands DPH for a stiff overconsolidated clay site. While each configuration of test equipment gives a different value of N_{10} the calculation of r_d brings the DPM and DPH closer and the calculation of q_d shows all three configurations giving very similar profiles.

The Figure E.2 shows data from an overconsolidated glacial till and includes data from DPL, DPM, DPH and DPSH. Here again the r_d values bring the profiles closer but calculation of q_d gives very similar profiles.

The use of q_d has the potential to allow the configuration of equipment to be varied down a profile as the blow counts fall too low (reduce the hammer mass) or rise too high (increase the hammer mass).



Key

I weathered London Clay

II unweathered London Clay

d depth

Figure E.1 — Data from DPL, DPM and DPH for a stiff overconsolidated clay site



Key

- I crust
- II weathered till
- III unweathered till
- IV silty sand
- d depth

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